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Motivation

Multilevel low rank (MLR) matrices are an extension of low rank matrices and factor models in the squared case. MLR generalize low rank matrices in the sense of giving a substantial reduction in storage and speed up in computing matrix-vector products, compared to a full dense matrix. MLR matrices are closely related to hierarchical matrices, which have been studied since at least the late 1980s [1, 2].

Multilevel low rank matrices

An $m \times n$ contiguous MLR matrix A with L levels has the form

$$A = A^1 + \cdots + A^L$$
,

where $A' = \mathbf{blkdiag}(A_{I,1}, \ldots, A_{I,p_I}), I = 1, \ldots, L$, and p_I is the size of the partition at level I, with $p_1 = 1$. We refer to $A_{l,k}$ as the kth block on level I of size $m_{l,k} \times n_{l,k}$. for l = 1, ..., L, $k = 1, ..., p_l$.

We require **rank** $A_{I,k} \leq r_I$, and for $I = 1, \ldots, L$, $k = 1, \ldots, p_I$ the factored form is

$$A_{I,k} = B_{I,k}C_{I,k}^{T}, \quad B_{I,k} \in \mathbf{R}^{m_{I,k} \times r_{I}}, \quad C_{I,k} \in \mathbf{R}^{n_{I,k} \times r_{I}}.$$

We refer to $r = r_1 + \cdots + r_L$ as the **MLR-rank** of *A*.

Example. The sparsity patterns of A^2 and A^3 are shown below.

* $A^2 =$ $A^3 =$ *

A general $m \times n$ MLR matrix \tilde{A} has the form

$$\tilde{A} = PAQ^T$$
,

where A is a contiguous MLR matrix, P and Q are permutation matrices.

Factor form. For each level $I = 1, \ldots, L$ define $\tilde{B}_l = \mathsf{blkdiag}(B_{l,1}, \ldots, B_{l,p_l}) \in \mathsf{R}^{m \times p_l r_l}, \qquad \tilde{C}_l = \mathsf{blkdiag}(C_{l,1}, \ldots, C_{l,p_l}) \in \mathsf{R}^{n \times p_l r_l}.$ Define $\tilde{B} = \begin{bmatrix} \tilde{B}_1 \cdots \tilde{B}_L \end{bmatrix} \in \mathbf{R}^{m \times s}, \qquad \tilde{C} = \begin{bmatrix} \tilde{C}_1 \cdots \tilde{C}_L \end{bmatrix} \in \mathbf{R}^{n \times s},$

with $s = \sum_{l} p_{l} r_{l}$. Then we can write A as $A = \tilde{B}\tilde{C}^{T},$

exactly the form of a low rank factorization of A.

Compressed factor form. We also arrange the factors into two arrays or matrices with dimensions $m \times r$ and $n \times r$. We vertically stack the factors at each level

$$B' = \begin{bmatrix} B_{l,1} \\ \vdots \\ B_{l,p_l} \end{bmatrix} \in \mathbf{R}^{m \times r_l}, \qquad C' = \begin{bmatrix} C_{l,1} \\ \vdots \\ C_{l,p_l} \end{bmatrix} \in \mathbf{R}^{n \times r_l}, \quad l = 1, \dots, L.$$

We horizontally stack these matrices to obtain two matrices

$$B = \begin{bmatrix} B^1 \cdots B^L \end{bmatrix} \in \mathbf{R}^{m \times r}, \qquad C = \begin{bmatrix} C^1 \cdots C^L \end{bmatrix} \in \mathbf{R}^{n \times r}.$$

parshakova.github.io

Two-matrix form

Factor Fitting, Rank Allocation, and Partitioning in Multilevel Low Rank Matrices Tetiana Parshakova¹ Trevor Hastie² Eric Darve³ Stephen Boyd⁴

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Our Contribution

- . We introduce a novel definition of multilevel low rank matrix.
- 2. We present two complementary block coordinate descent algorithms for factor fitting.
- 3. We present a greedy algorithm for rank allocation that is able to re-allocate the rank assigned to each level in the hierarchy, to improve the fitting.
- 4. An open-source package that implements these methods, github.com/cvxgrp/mlr_fitting.

General MLR fitting

| 'n | The most general | MLR fitting | problem is |
|----|------------------|-------------|------------|
| | | | |

minimize $||A - \hat{A}||_F^2$ subject to \hat{A} is rank r MLR,

where $A \in \mathbb{R}^{m \times n}$ is the given matrix to be fit, \hat{A} is the variable. In this general version of the problem the data are A, the matrix to be fit, and r, the rank.

We seek permutations P and Q, the number of levels L, the block dimensions $m_{l,k}$ and $n_{l,k}$, $l = 1, \ldots, L$, $k = 1, \ldots, p_l$, the two matrices B and C, and the rank allocation, *i.e.*, r_i for which $r_1 + \cdots + r_l = r$.

Factor fitting

We fix the combinatorial aspects of \hat{A} , and only optimize over the (real) coefficients in the factors, *i.e.*, the matrices B and C. We propose to use 1) block coordinate descent and 2)alternating least squares for factor fitting.

Rank allocation

We fix the hierarchical partition but not the ranks, *i.e.*, we optimize over B and C, and also the ranks r_1, \ldots, r_L , subject to $r_1 + \cdots + r_L = r$. The rank allocation problem is a natural one when the hierarchical row and column partitions are given or already known.

Define the residual matrix

$$R = \tilde{A} - \sum_{j \neq l} \mathbf{blkdiag}(B_{j,1}C_{j,1}^T, \dots, B_{j,p_j}C_{j,p_j}^T)$$

If we increase/decrease the rank allocated to (each block of) level / by 1, the decrease/increase in Frobenius norm squared error is

$$\delta_{I}^{+} = \sum_{k=1}^{p_{I}} \sigma_{r_{I}+1}^{2}(R_{I,k}), \qquad \delta_{I}^{-} = \sum_{k=1}^{p_{I}} \sigma_{r_{I}}^{2}(R_{I,k}).$$

These numbers predict the decrease or increase when only the level *I* factors are changed. In each iteration of the rank allocation algorithm, we find the level i and j, with $i \neq j$, for which the predicted net decrease is maximized

$$i, j = \underset{i \neq j}{\operatorname{argmax}} \left(\delta_i^+ - \delta_j^- \right).$$

Numerical Experiments

The discrete Gauss transform (DGT) matrix is given by

$$A_{ij} = e^{-\|t_i - s_j\|_2^2/h^2}$$

where $s_j \in \mathbf{R}^d$ for j = 1, ..., n and $t_i \in \mathbf{R}^d$ for i = 1, ..., m are source and target locations respectively and h > 0 is the bandwidth. We set sources and targets to be uniformly distributed in a unit cube $[0,1]^d$ with d = 3, m = 5000, n = 7000, and h = 0.2. We fix the rank as r = 28.



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Figure 1. Fitting error during rank allocation, starting from three different initial allocations of rank.



Figure 2. Rank r = 28 partitioning across L = 14 levels during fitting of DGT matrix, starting from the bottom level l = 14, uniform and the top level l = 1 initial allocation.

References

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[1] Leslie Greengard and Vladimir Rokhlin A fast algorithm for particle simulations Journal of Computational Physics, 73(2):325–348, 1987. [2] Wolfgang Hackbusch. Hierarchical matrices: algorithms and analysis, volume 49.